

Modelica Model Debugging

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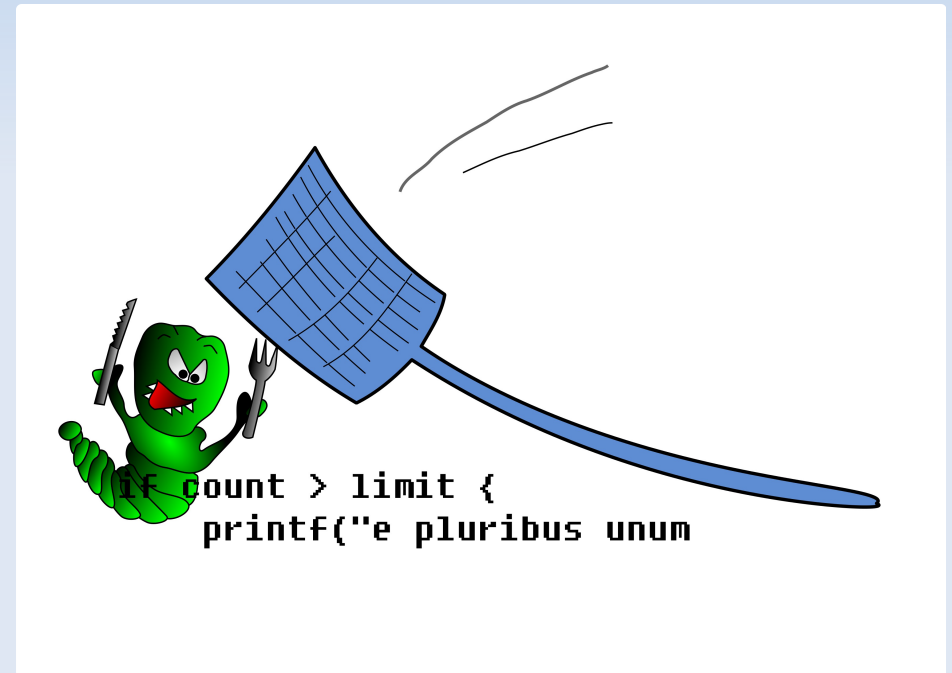
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Modelica

- No explicit control flow
- Optimization
- Symbolic manipulations
- Numerical methods and solvers
- Linear/Non-linear blocks
- Events

Modelica Debugging

- Need knowledge
 - Modelica
 - The tool
 - Numerical methods



Typical Error Message

Error solving nonlinear system 132

time = 0.002

residual[0] = 0.288956

x[0] = 1.105149

residual[1] = 17.000400

x[1] = 1.248448

...

Better Error Message

Error solving nonlinear system 132 <[more info](#)>

time = 0.002

residual[0] = 0.288956

x[0] = 1.105149

residual[1] = 17.000400

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...

Origin

- Several Levels
 - (Graphical Representation)
 - Source Code
 - Flat Equation-System
 - Optimized Equation-System
 - Translated Code (typically C)
- It should always be possible to go backwards
 - Simple for flattened equation system to source
 - Harder for optimized code

Symbolic Transformations

- From source code to flat equations
 - Most of the structure remains
 - Few symbolic manipulations (mostly simplification/evaluation)
- Equation System Optimization
 - Changes structure
 - Strong connected components
 - Variable replacements
 - ... and more

Tracing Transformations

- Simple Idea
 - Store transformations as equation metadata
 - Works best for operations on single equations
- Each kind of transformation is different
 - Alias Elimination ($a = b$)
 - Gaussian Elimination (linear systems, several equations)
 - Equation solving ($f_1(a,b) = f_2(a,b)$, solve for a)
 - ...

Alias Elimination

- `boxBody1.body.w_a[3] = revolute1.w`
- Can remove one variable and replace it with the other

~~`boxBody1.body`~~`revolute1.w`~~`_a[3]`~~ + `revolute2.w`

Operations

- Simplify
- Substitution
 - Alias elimination
 - Known variables
- Inline
- Scalarization
- Differentiation
- Solve w.r.t.
- Solve linear system symbolically
- New dummy derivative added
- Residual form



Debugging Using the Trace

- General Purpose
 - Verify performance and correctness of the trace
 - Navigate equations
 - Cross-referencing
 - Go to parents
 - View trajectories
- Special-Purpose
 - Non-linear system debugger

Trace Example

Demo

+simCodeTarget=Dump

Future Work

- Graphical debugger
 - General-purpose
 - Domain-specific
- Cross-references, parent blocks
- Runtime support to launch debugger
- Tracing in algorithmic code
- More operations recorded
 - Control flow and events
 - Forgotten optimization modules

